

Investigations at the Interface of Morphology, Evolution and Cognition

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Simulated robots are evolved in a virtual environment. This approach can illuminate the ultimate mechanisms of behavior: what environments and selection pressures favor particular useful morphological and neurological structures?

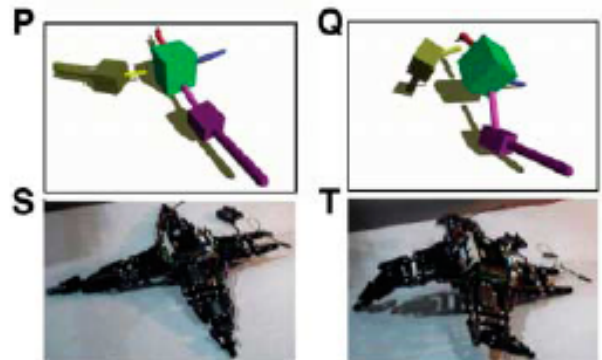


Illustration from “Resilient Machines Through Continuous Self-Modeling”, *Science*, 314: 1118-1121, 2007.

**Monday, September 13, 2010
5:00 PM in Lecture Hall 2**

Fall 2010 EvoS Seminar Series
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